

# A 360-Degree and -Order Model of Venus Topography

NICOLE RAPPAPORT AND JEFFREY J. PLAUT

*Jet Propulsion Laboratory, California Institute of Technology, 4800 Oak Grove Drive, Pasadena, California 91109*  
E-mail: njb@nomad.jpl.nasa.gov

Received June 1, 1994; revised September 9, 1994

This report presents the most recent spherical harmonic topography model of Venus developed at Jet Propulsion Laboratory. It was produced by a spherical harmonic analysis of the most complete set of Magellan altimetry data, augmented by Pioneer Venus and Venera data. The harmonic coefficients of the topography were computed to degree and order 360. Compared to previous topography models, this one has the highest correlation with the gravity field of Venus. © 1994 Academic Press, Inc.

## 1. INTRODUCTION

This report provides the scientific community with the latest spherical harmonic topographic model of Venus produced at the Jet Propulsion Laboratory (JPL). The data set that was used is described in Section II. Section III presents the harmonic analysis of Venus' topography. Section IV presents scientific implications. Section V contains a summary.

## II. DATA

The starting point for building the set of data that were analyzed was the GTDR files, which contain maps of Magellan altimetry data, produced by the Massachusetts Institute of Technology for the Magellan Project (Ford and Pettengill 1992). These data cover the planet by means of three maps: a Mercator projection map and two polar maps. These maps provide the most internally consistent version of the Magellan altimetry data set (P. Ford, personal communication). The maps were projected and averaged into a cylindrical grid of  $0.25^\circ \times 0.25^\circ$ . The original data have a pixel size of  $\sim 5$  km. Hence, the reprojection process reduces the resolution of the data set, especially at low latitudes. Overall, every sample of our topography model is based on a number of Magellan altimetry data points.

We follow Bills and Kobrick (1985) and Konopliv *et al.* (1993) and use a rectangular grid. This is intuitively

justified from the behavior of the harmonic functions: each harmonic function has the same number of zeroes on each parallel. Furthermore, because of the method that we use to compute the harmonic coefficients, each data point is effectively weighted by the area of the corresponding cell.

The pre-Magellan topography model (TOPODR.4.0; Yewell 1993), which consisted of data from Pioneer Venus Orbiter (PVO) altimetry merged with Venera 15/16 altimetry, was used to fill gaps.

At this point, three gaps remained in the data. The two main gaps are located near the south pole, and a smaller gap is present near the north pole. These gaps have two separate origins: orbits during superior conjunction and orbits affected by the thermal hide strategy, in which the High Gain Antenna was used to shadow the spacecraft, precluding altimetry observations.

Our first topography model of Venus used a less complete set of Magellan anti PVO altimetry data and a least squares method to compute the harmonic coefficients of the topography to order and degree 21 (McNamee *et al.* 1993). The least squares method did not require that the gaps be filled. Our second topography model used a more complete set of data and a computation by quadrature to obtain the coefficients to degree and order 20 (Konopliv *et al.* 1993). This new method required that no gap be present in the data. Therefore, we filled the gaps by using topographical heights computed from the  $21 \times 21$  model. The same quadrature method is used in this paper. The gaps were filled by using the  $120 \times 120$  model. Finally, we obtained a complete set of data referenced to the Venus body-fixed reference frame, as defined by Davies *et al.* (1992).

## III. HARMONIC ANALYSIS OF THE TOPOGRAPHY

The planetary radius at latitude  $\varphi$  and longitude  $\lambda$  with respect to the body-fixed reference frame defined by the Venus rotation axis and prime meridian is written as

$$= R_1 \sum_{\ell=0}^{+\infty} \sum_{m=0}^{\ell} P_{\ell m}(\sin \varphi) \quad (1)$$

$$(C_{\ell m}^t \cos m\lambda + S_{\ell m}^t \sin m\lambda),$$

, is the equatorial radius, the  $C_{\ell m}^t$  and  $S_{\ell m}^t$  are the reduced harmonic coefficients of the topography and  $P_{\ell m}$  are the normalized Legendre functions.

### Method

are two methods of computing the harmonic coefficients of the topography. The first method consists of least squares fit of Eq. (1) to the data. In practice, the least squares method requires too much computing when the desired degree is high. A much less computationally expensive method consists of computing the coefficients independently, as integrals. The coefficients are given by

$$C_{\ell m}^t = \frac{1}{4\pi R_0} \int_{-\pi/2}^{\pi/2} \cos \varphi \, d\varphi \int_0^{2\pi} d\lambda (R(\varphi, \lambda) - R_0) P_{\ell m}(\sin \varphi) \cos m\lambda, \quad (2)$$

$$S_{\ell m}^t = \frac{1}{4\pi R_0} \int_{-\pi/2}^{\pi/2} \cos \varphi \, d\varphi \int_0^{2\pi} d\lambda (R(\varphi, \lambda) - R_0) P_{\ell m}(\sin \varphi) \sin m\lambda,$$

$R_0$  is an a priori reference radius. These coefficients are relative to  $R_0$ . They are rescaled by introducing a new radius  $R_1$  such that  $C_{00} = 1$ . In practice, the integral over the unit sphere must be replaced by a sum of terms. Each term corresponds to a pixel defined by  $\varphi_i - \delta\varphi/2 \leq \varphi \leq \varphi_i + \delta\varphi/2$ ,  $\lambda_j - \delta\lambda/2 \leq \lambda \leq \lambda_j + \delta\lambda/2$  with  $\delta\varphi = \delta\lambda = 0.25^\circ$ . Furthermore, the integral must be modified to take into account the fact that the radius of the planetary radius in each pixel is a mean value over that pixel. We used the procedure devised by Ford (1993) to compute the integrals.

### Results

The harmonic coefficients of the topography were computed from individual integrals to degree and order 360. The radius of Venus is found to be  $R_1 = 6051,848$  km. Our determinations led to  $R_1 = 6051,448$  km (Bills and Kibrick 1985),  $R_1 = 6051,839$  km (McNamee *et al.* 1993), and  $R_1 = 6051,839$  km (Konopliv *et al.* 1993). The difference between Bills and Kibrick determination and our determinations by McNamee *et al.* and Konopliv *et al.* is due to the fact that Bills and Kibrick used preliminary data that were not completely reduced. The difference between the two latter determinations is due to the fact that the altimetry data

TABLE I  
Normalized Harmonic Coefficients of the Topography to Degree 5

$\ell$	$m$	$C_{\ell m}$	$S_{\ell m}$
1	0	$(-1.0579 \pm 0.02) \times 10^{-6}$	
1	1	$(-1.94395 \pm 0.001) \times 10^{-5}$	$(1.7864 \pm 0.003) \times 10^{-5}$
2	0	$(-2.5917 \pm 0.002) \times 10^{-5}$	
2	1	$(1.4489 \pm 0.002) \times 10^{-5}$	$(-8.5456 \pm 0.03) \times 10^{-6}$
2	2	$(-2.1616 \pm 0.002) \times 10^{-5}$	$(-3.3037 \pm 0.01) \times 10^{-6}$
3	0	$(3.0047 \pm 0.002) \times 10^{-5}$	
3	1	$(4.7410 \pm 0.002) \times 10^{-5}$	$(-7.9826 \pm 0.02) \times 10^{-6}$
3	2	$(4.4193 \pm 0.03) \times 10^{-6}$	$(2.3180 \pm 0.004) \times 10^{-5}$
3	3	$(-9.1018 \pm 0.02) \times 10^{-6}$	$(-8.0818 \pm 0.02) \times 10^{-6}$
4	0	$(2.6756 \pm 0.0006) \times 10^{-5}$	
4	1	$(6.8970 \pm 0.03) \times 10^{-6}$	$(1.4741 \pm 0.006) \times 10^{-5}$
4	2	$(1.5841 \pm 0.002) \times 10^{-5}$	$(8.3783 \pm 0.03) \times 10^{-6}$
4	3	$(-4.71425 \pm 0.02) \times 10^{-6}$	$(-3.7523 \pm 0.01) \times 10^{-5}$
4	4	$(8.4789 \pm 0.03) \times 10^{-6}$	$(3.0146 \pm 0.003) \times 10^{-5}$
5	0	$(-8.7303 \pm 0.02) \times 10^{-6}$	
5	1	$(2.0695 \pm 0.002) \times 10^{-5}$	$(2.3163 \pm 0.001) \times 10^{-5}$
5	2	$(4.0665 \pm 0.02) \times 10^{-6}$	$(-1.3484 \pm 0.003) \times 10^{-5}$
5	3	$(7.6344 \pm 0.03) \times 10^{-6}$	$(1.8850 \pm 0.001) \times 10^{-5}$
5	4	$(8.6339 \pm 0.02) \times 10^{-6}$	$(6.4104 \pm 0.2) \times 10^{-7}$
5	5	$(1.0987 \pm 0.0008) \times 10^{-5}$	$(-7.8237 \pm 0.01) \times 10^{-6}$

that we used in this paper were substantially improved with respect to the data used in the two previous papers. This improvement is a consequence of a reduction in the orbital errors.

The harmonic coefficients up to degree 2 are given in Table 1. In order to obtain an order of magnitude of the uncertainties in the coefficients, we performed three additional calculations in which the data were modified by adding  $\pm 80$  m to each data point, where the sign was chosen randomly for each point. The uncertainties listed in Table 1 correspond to the maximum difference between the nominal case and the three cases where the data quality had been artificially degraded. These uncertainties are pessimistic, first because the error of  $\pm 80$  m is itself pessimistic, and then because they cumulate the errors made in the three cases where the data were degraded. On the other hand, the method that we used to evaluate the uncertainties in the individual coefficients assumes that the errors in the topographic heights are uncorrelated and does not take into account the over-sampling near the pole, and in that sense it may be optimistic.

Figure 1 shows topography contours obtained with our topography model. Figure 2, which shows the topography along the equator, both as given by the data (continuous line) and as computed from the model (black triangles), indicates that there is a good agreement between the model and the data. Figure 3 contains a plot of the difference between the topography along the equator computed from the model and the observed topography. This plot

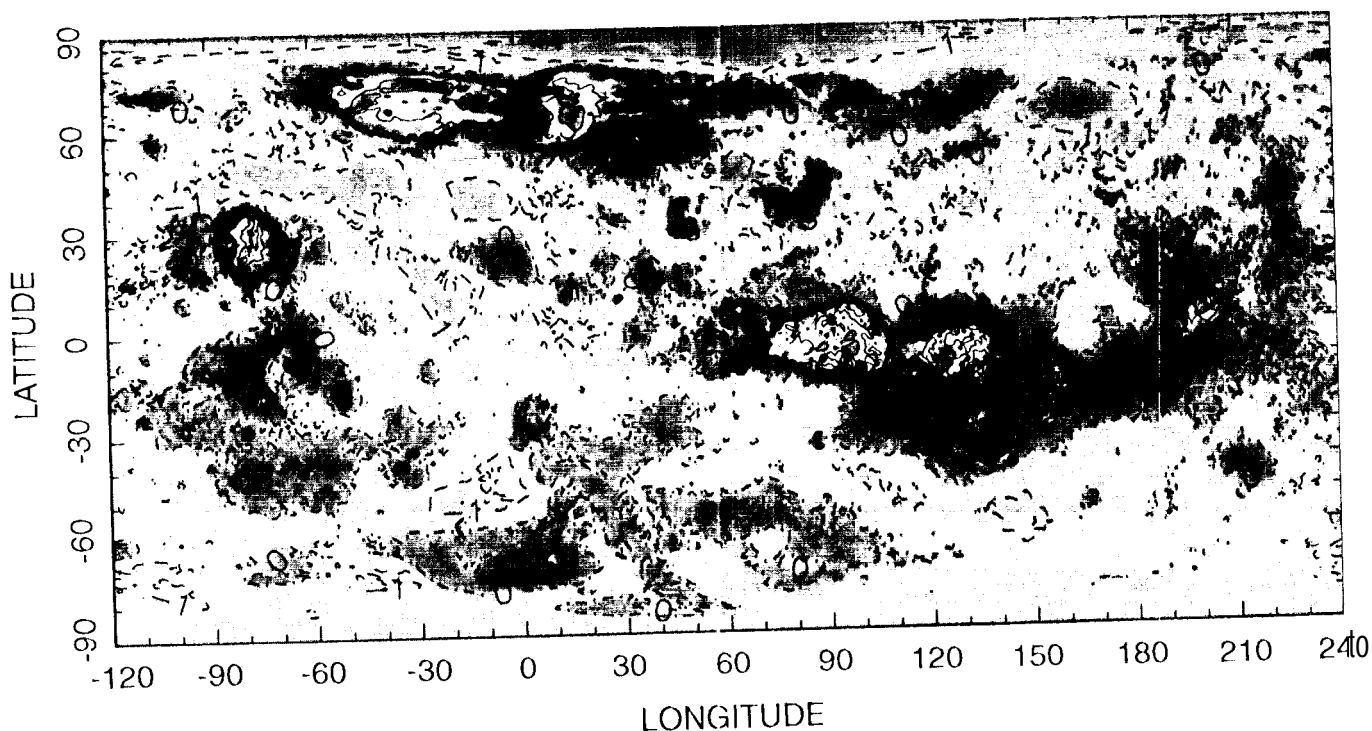


FIG. 1. Topography map produced by using this paper's 360 $\times$  360 topography model. The zero level correspond to Venus' mean radius  $R_f = 6051.848$  km. The topography contours are separated by 1 km.

shows that the error in the model is due to the high-frequency terms.

Our topography model can be obtained by writing to the authors of the paper and it will be archived in the

Planetary Data System Geosciences Node at Washington University (Saint Louis, MO).

#### IV. IMPLICATIONS

This section is devoted to scientific results obtained from our model.

##### IV.1, Geometrical Implications

Since the flattening of Venus is very small, its topography can be approximated by a sphere off-set from the origin of the coordinate system, which is Venus' center of mass. According to this definition of the offset between the center of mass and the center of figure, the location of the center of figure is given by

$$\begin{aligned} X_f &= R_f C_{11} = 118 \text{ m}, \\ Y_f &= R_f S_{11} = 108 \text{ m}, \\ Z_f &= R_f C_{10} = 6 \text{ m}. \end{aligned} \quad (3)$$

The above definition is used by scientists who are interested in understanding the internal structure of Venus. On the other hand, there exist other areas of planetary sciences where scientists use approximations of planetary

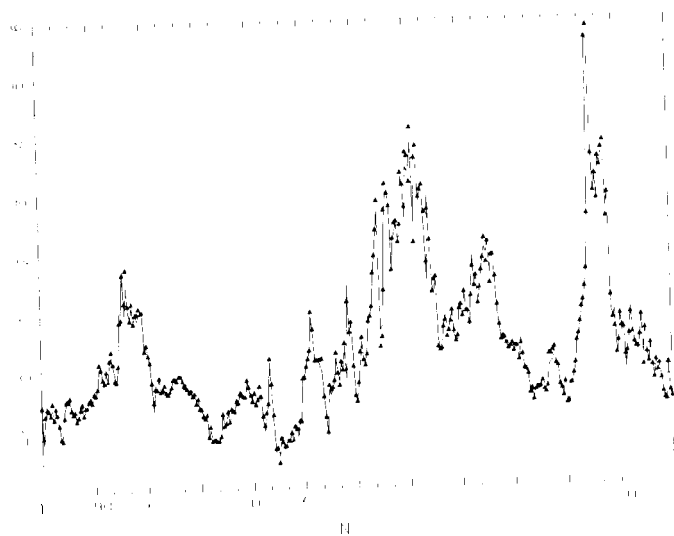


FIG. 2. Topography along the equator from the data (continuous line) and as computed from our model (black triangles), with respect to the reference radius. The vertical scale is in kilometers.

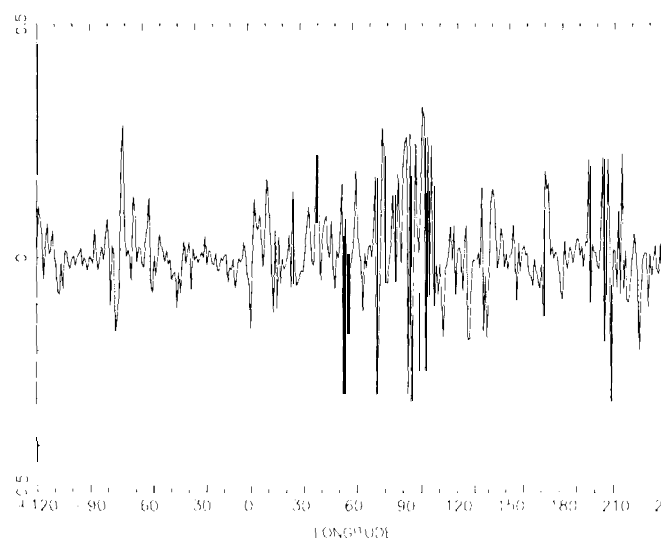


FIG. 3. Difference between the topography along the equator computed from the model and the observed topography. The vertical scale is in kilometers.

body's shapes as ellipsoids offset from the center of mass (Davies *et al.* 1992). An example of a situation in which the ellipsoid model is useful is that of occultation experiments.

To first order with respect to the harmonic coefficients, the location of the center of figure of the ellipsoid is given by Eq. (3). A more accurate method consists of fitting an offset ellipsoid by least squares to the topography. This calculation yields

$$X_f = -205 \text{ m},$$

$$Y_f = 181 \text{ m},$$

$$Z_f = 71 \text{ m},$$

which corresponds to the latitudinal coordinates

$$r_f = 282 \text{ m},$$

$$\varphi_f = 14^\circ,$$

$$\lambda_f = 139^\circ$$

and indicates that the center of figure lies under the northeast part of Thetis Regio.

The least square fit also gives the orientation and the length of the principal axes of figures. These are given in Table 11, together with the orientation of the principal axes of inertia. The axes of figures and the axes of inertia do not coincide. The orientation of the axes of figures is governed by the equatorial and mid-latitude highlands. The longest axis of figure passes through Phoebe Regio

and Niobe Planitia, North of Ovda in Western Aphrodite. The second axis of figure passes through Eistlia Regio and South of Atla in Eastern Aphrodite.

## 1 V.2. Statistical Implications

The rms magnitude of the normalized coefficient, defined by

$$\text{rms}(\ell) = \sqrt{\frac{\sum_{m=0}^{\ell} (C_{\ell m}^t)^2 + (S_{\ell m}^t)^2}{2\ell + 1}}, \quad (4)$$

where the sum goes from  $m=0$  to  $m=\ell$  is shown on Fig. 4, in logarithmic scale. As in Section 111.2, we degraded the topography data by adding randomly  $\pm 80$  m to each data point in order to estimate uncertainties in the spectrum. Even though the individual coefficients change, the spectrum remains very stable and the curve corresponding to the degraded topography data practically coincide with the nominal curve.

For  $\ell > 100$ , the slope of the spectrum changes and the spectrum becomes flatter. This may not be a real property of the spectrum but rather an artifact associated with our method. As mentioned in Section 111.2, the errors in the topography model are essentially in the high-frequency terms. One possibility is that the oversampling at high latitude had the effect of producing too much power in the high-degree harmonic coefficients.

We compared the variance of the observed topography with the variance of the topography computed from our model. Denoting by  $f$  the topography, the variance was computed using the equation

$$\sigma_f^2 = \frac{1}{S} \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} [f(\varphi, \lambda) - \bar{f}]^2 dS, \quad (5)$$

where  $dS$  represents an element of surface and

TABLE 11

Orientation of the Principal Axes of Figures and of the Principal Axes of Inertia of Venus

	Axes of figure	Axes of inertia
Latitude	13.8°	0.2°
Longitude	98.2°	-2.9°
Length	6052.3 km	
Latitude	23.3°	0.4°
Longitude	11.2°	87.1°
Length	6051.8 km	
Latitude	64.9°	89.5°
Longitude	168.4°	117.3°
Length	6051.4 km	

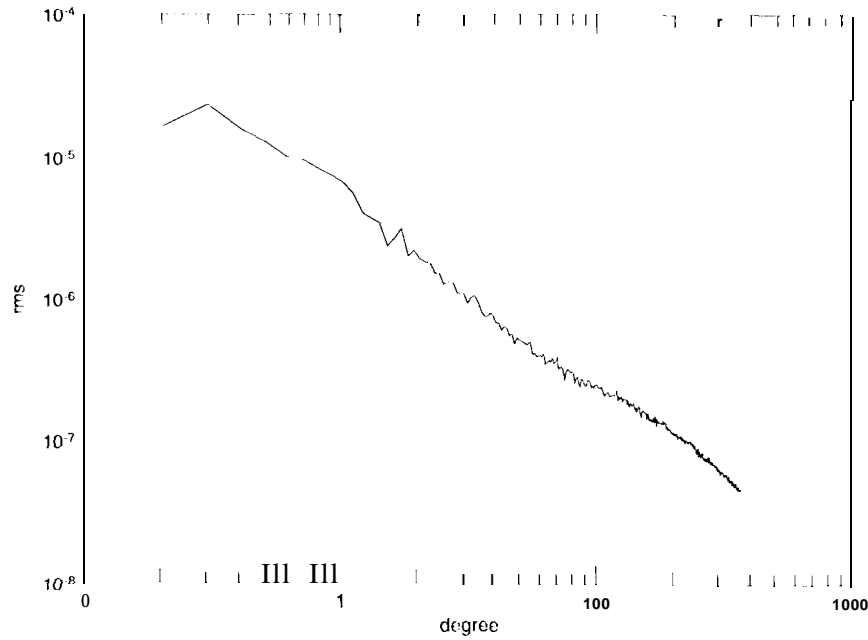


FIG. 4. Rms magnitude of the normalized coefficient of the topography on a logarithmic scale.

$$\bar{f} = \frac{1}{S} \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} f(\varphi, \lambda) dS. \quad (6)$$

With the observed topography, we obtained  $\sqrt{\sigma_f} = 0.943$  while our model gives an almost equal value of  $\sqrt{\sigma_f} = 0.941$ . The agreement between these two values is due to the fact that the variance is essentially due to the low-degree terms and does not allow one to rule out that the model overestimates the power of the high-degree harmonic coefficients.

The correlation between Venus' topography and gravity was also investigated. The gravity field at a point  $P$  outside the planet is

$$U(r', y, \lambda) = \frac{GM}{r} \sum_{\ell=2}^{\infty} \sum_{m=0}^{\ell} \left( \frac{R_g}{r} \right)^{\ell} P_{\ell m}(\sin \varphi) (C_{\ell m}^g \cos m\lambda - S_{\ell m}^g \sin m\lambda), \quad (7)$$

where  $G$  is the gravitational constant,  $M$  is the mass of the planet,  $R_g$  is a reference radius, and the  $C_{\ell m}^g, S_{\ell m}^g$  are the harmonic coefficients of the gravity field.

The correlation per degree was computed as

$$\gamma(\ell) = \frac{\sum C_{\ell m}^t C_{\ell m}^g + S_{\ell m}^t S_{\ell m}^g}{\sqrt{\sum (C_{\ell m}^t)^2 + (S_{\ell m}^t)^2} \sqrt{\sum (C_{\ell m}^g)^2 + (S_{\ell m}^g)^2}}, \quad (8)$$

where the sums go from  $m=0$  to  $m=\ell$ . It is shown in

Fig. 5 for three topography models, the one by Konopliv *et al.* (1993), the one by Balmino (1993), and the model presented in this paper. All calculations used the most recent gravity field model of Konopliv and Sjogren (1994). The uncertainty in the correlation due to the errors in the harmonic coefficients of the topography was computed

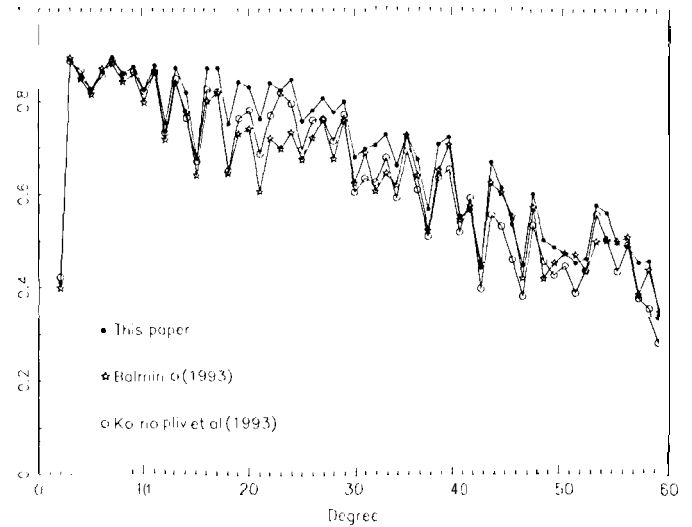


FIG. 5. Correlation per degree between Venus' topography and its gravity field, comparing the topography model of Konopliv *et al.* (1993), the model of Balmino (1993), and this paper's topography model; all calculations use the most recent gravity field model of Konopliv and Sjogren (1994).

TABLE 111  
Correlations between Venus' Topography and Its Gravity Field  
over Seven Regions and over the Entire Planet

Regio	$\varphi_{\min}$	$\varphi_{\max}$	$\lambda_{\min}$	$\lambda_{\max}$	$\gamma_1$	$\gamma_2$	$\gamma_3$
Beta	1° 0'	40°	105°	55°	0.877	0.819	0.934
Phoebe	25°	10°	-90°	50°	0.765	0.821	0.845
Maxwell	45°	80°	60°	30°	0.842	0.857	0.864
Gula	0°	30°	15°	30°	0.890	0.897	0.918
Bell	0°	40°	30°	60°	0.775	0.799	0.812
Ovda	15°	10°	75°	110°	0.790	0.794	0.805
Atla	10°	30°	180°	210°	0.949	0.964	0.968
Planet	90°	90°	120°	240°	0.753	0.745	0.772

Note.  $\gamma_1$  is based on the topography model of Konopliv *et al.* (1993);  $\gamma_2$  uses the topography model of Balmino (1993);  $\gamma_3$  is based on this paper's topography model; all calculations use the most recent gravity field model of Konopliv and Sjogren (1994).

as above, by comparing the nominal correlation with the correlation obtained by degrading the topography data. We found that it was negligible. The error bars due to the errors in the gravity field coefficient are shown in Fig. 10 of Konopliv and Sjogren (1994).

Balmino's model was obtained from a least squares procedure. Balmino (1993) checked that the two methods give the same results if the same data sets are used.

Our model has the highest correlation with the gravity field. Since it is very unlikely that this highest correlation is due to chance, we infer that the highest correlation indicates improvement over previous models.

The correlation at degree 2 is much less than for the other low-degree harmonic coefficients. This is probably related to the fact that Venus' rotation has been tidally slowed down over the age of the Solar System and the harmonic coefficients of degree 2 have nothing to do with adjustment to hydrostatic equilibrium.

We also computed regional correlations in the following way. Denoting by  $g$  the gravity at the surface and using Eqs. (6) and (5) to compute  $\bar{g}$  and  $\sigma_g$ , the regional correlation is given by

$$\gamma = \frac{(1/S) \int \int (f - \bar{f})(g - \bar{g}) dS}{\sqrt{\sigma_f \sigma_g}} \quad (9)$$

Regional correlations over seven regions of Venus are listed in Table 111 for the three above-mentioned topography models. Again, our model gives the highest correlations. Among the seven regions that we studied, the highest correlations are obtained in Beta Regio and Atla Regio. These highlands are also characterized by moderately negative Bouguer anomalies and abundant volcanism which suggest dynamic support of the topography. The

lowest correlations were obtained in Ovda Regio. Ovda is characterized by very large negative Bouguer anomalies and complex ridged terrains or tesserae, which suggest essentially passive isostasy associated with crustal thickening.

## V. SUMMARY

The first purpose of this paper is to make available to the scientific community the best model developed at the JPL. Models of Venus topography in spherical harmonics are useful for studying the geophysics of this planet. Examples of recent work using such models are found in Banerdt *et al.* (1994), Kucinskas and Turcotte (1994), and Simmons *et al.* (1994).

The second purpose of this paper is to present some geometrical and statistical implications of this model. The scientific conclusions are:

(a) The offset between the center of mass and the center of figure is about 10 times smaller than the offset in Earth, the Moon, and Mars. The center of figure of Venus lies under Aphrodite.

(b) The orientation of the principal axes is determined by the equatorial and mid-latitude highlands.

(c) The topography and the gravity field of Venus are very strongly correlated. Regional correlations are higher in Beta Regio and Atla Regio, which are thought to be dynamically supported, than in Ovda Regio, which is thought to be essentially supported by passive isostasy.

(d) The rms spectrum of the topography follows a power law up to degree  $l \approx 100$ . The flattening of the rms spectrum for  $l > 100$  may not be real.

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